



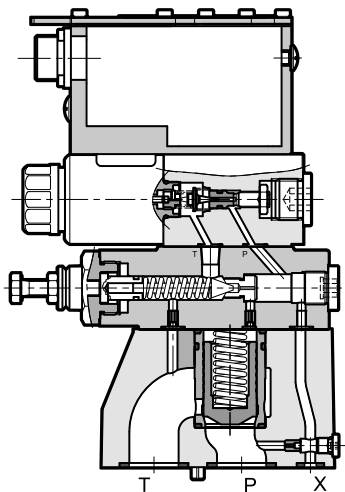
# PRE\*G\*

## PROPORTIONAL PRESSURE RELIEF VALVES, PILOT OPERATED, WITH INTEGRATED ELECTRONICS

### SUBPLATE MOUNTING ISO 6264

**p** max **350** bar  
**Q** max (see table of performances)

### OPERATING PRINCIPLE



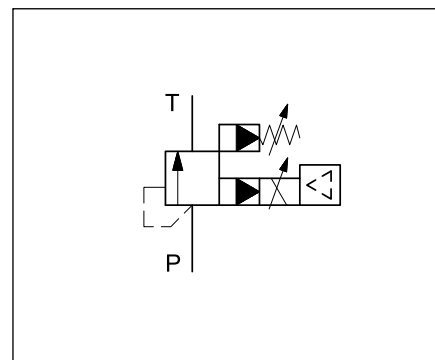
- The PRE\*G\* valves are proportional pressure relief valves, pilot operated, with integrated electronics and mounting interface in compliance with ISO 6264 standards.
- These valves are used to control hydraulic circuit pressure and enable the use of the full flow rate of the pump, even with settings approaching calibrated values.
- The two-stage design and wide passages ensure reduced pressure drops thereby improving the system energy performance.
- They are fitted with a manual pressure relief valve which is factory set to  $\geq 15\%$  of the maximum value in the pressure control range.
- Valves are available with different types of electronics, with analogue or fieldbus interfaces.
- They are available in three sizes with flow rates up to 500 l/min and in four pressure control ranges up to 350 bar.
- The valves are easy to install. The driver directly manages digital settings.

### PERFORMANCES

(obtained with mineral oil with viscosity of 36 cSt at 50 °C and p = 140 bar)

		PRE10G*	PRE25G*	PRE32G*
Maximum operating pressure	bar	350		
Maximum flow	l/min	200	400	500
Step response		see point 8		
Hysteresis	% of p nom	< 3%		
Repeatability	% of p nom	< ±1%		
Electrical characteristic		see point 3		
Ambient temperature range	°C	-20 / +60		
Fluid temperature range	°C	-20 / +80		
Fluid viscosity range	cSt	10 ÷ 400		
Fluid contamination degree	According to ISO 4406:1999 class 18/16/13			
Recommended viscosity	cSt	25		
Mass	kg	5.5	6.3	8.5

### HYDRAULIC SYMBOL



## 1 - IDENTIFICATION CODE

### 1.1 - Standard electronics

P	R	E		G	-	/	32		-		K11		
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Pilot operated pressure relief valve

Electro-proportional control

Size: \_\_\_\_\_  
**10** = ISO 6264-06  
**25** = ISO 6264-08  
**32** = ISO 6264-10

**Standard electronics for pressure control in open loop**

Pressure control range \_\_\_\_\_  
**070** = up to 70 bar      **210** = up to 210 bar  
**140** = up to 140 bar      **350** = up to 350 bar

Series No. \_\_\_\_\_  
 (the overall and mounting dimensions remain unchanged from 30 to 39)

Option:  
**/ W7** = Zinc-nickel surface treatment (see **NOTE**)  
 Omit if not required

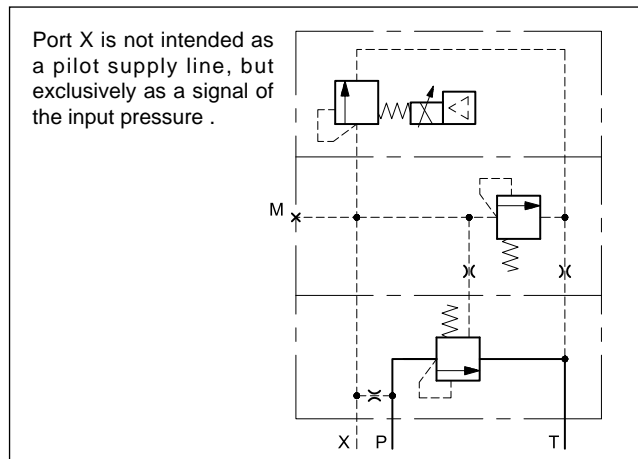
Pin C function:  
**A** = external enable  
**B** = internal enable  
**C** = 0V monitor

Connection 6 pin + PE

Reference signal:  
**E0** = voltage 0 ÷ 10 V      **E1** = current 4 ÷ 20 mA

Seals:  
**N** = NBR seals for mineral oil (**standard**)  
**V** = FPM seals for special fluids

### 1.2 - Detailed symbol



**NOTE:** The standard valve is supplied with surface treatment of phosphating black on the valve body.

The zinc-nickel finishing makes the valve suitable to ensure a salt spray resistance up to 240 hours (test operated according to EN ISO 9227 standards and test evaluation operated according to UNI EN ISO 10289 standards).

### 1.3 - Compact electronics

P	R	E		GL	-	/			-		K12		
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Pilot operated pressure relief valve

Electro-proportional control

Size: \_\_\_\_\_  
**10** = ISO 6264-06  
**25** = ISO 6264-08  
**32** = ISO 6264-10

**Digital integrated electronics for open loop compact box**

Pressure control range \_\_\_\_\_  
**070** = up to 70 bar      **210** = up to 210 bar  
**140** = up to 140 bar      **350** = up to 350 bar

Series No. (the overall and mounting dimensions remain unchanged from 10 to 19):  
**10** = versions with E0, E1 and CA interfaces  
**12** = version with IOL interface

Option:  
**/ W7** = Zinc-nickel surface treatment (see **NOTE** p. 1.1)  
 Omit if not required

Connection 5 pin M12

Interfaces:  
**E0** = analogue, voltage 0 ÷ 10 V  
**E1** = analogue, current 4 ÷ 20 mA  
**IOL** = IO-Link interface  
**CA** = CAN Open

Seals:  
**N** = NBR seals for mineral oil (**standard**)  
**V** = FPM seals for special fluids

#### 1.4 - Electronics with fieldbus communication

<b>P</b>	<b>R</b>	<b>E</b>		<b>GH</b>	<b>-</b>		<b>/ 32</b>		<b>-</b>		<b>K16</b>	<b>/</b>				
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Pilot operated pressure relief valve

Electro-proportional control

Size: \_\_\_\_\_  
**10** = ISO 6264-06  
**25** = ISO 6264-08  
**32** = ISO 6264-10

**Digital integrated electronics for open loop with fieldbus communication**

Pressure control range \_\_\_\_\_  
**070** = up to 70 bar      **210** = up to 210 bar  
**140** = up to 140 bar      **350** = up to 350 bar

Series No. (the overall and mounting dimensions remain unchanged from 30 to 39) \_\_\_\_\_

Seals: \_\_\_\_\_  
**N** = NBR seals for mineral oil (**standard**)  
**V** = FPM seals for special fluids

Reference signal: \_\_\_\_\_  
**E0** = voltage 0 ÷ 10 V  
**E1** = current 4 ÷ 20 mA  
**FD** = full digital version (on request)

Option:  
**/ W7** = zinc-nickel surface treatment (see p. 1.2)  
 Omit if not required.

X4 Analogue transducer:  
**0** = none  
**1** = single/double transducer

X7 Digital transducer:  
**0** = none  
**1** = SSI type

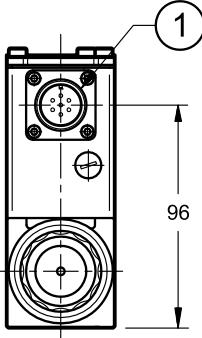
X2, X3 Fieldbus type:  
**EC** = EtherCAT  
**EN** = Ethernet /IP  
**PN** = Profinet

X1 Main connection configuration:  
**D1** = one command  
**D0** = full digital version (on request - available for reference signal FD type only)

Main connection 11 pin + PE

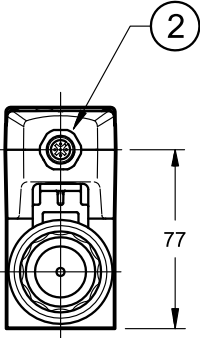
#### 2 - COMPARISON AMONG INTEGRATED ELECTRONICS

**G type**



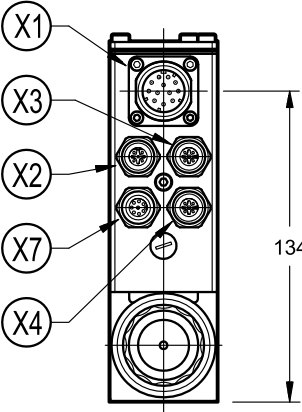
96

**GL type**



77

**GH type**



134

dimensions in mm

1	Connection 6 pin + PE
2	Connection M12 5 pin, code A, male
X1	Main connection 11 pin + PE
X2	Fieldbus communication (IN)
X3	Fieldbus communication (OUT)
X4	Connection for analogue transducer
X7	Connection for digital transducer

**NOTE 1:** Depending on the chosen version, X4 and X7 connections may not be present. Please refer to sections 4, 5 and 6 for connections descriptions and pinouts.

**NOTE 2:** Related mating connectors have to be ordered separately. See catalogue 89 000.

## 3 - ELECTRONICS COMMON DATA

Duty cycle		100% (continuous operation)
Protection class according to EN 60529		IP65 / IP67 ( <b>NOTE</b> )
Supply voltage	V DC	24 (from 19 to 30 VDC), ripple max 3 Vpp
Power consumption	VA	25
Maximum solenoid current	A	1.88
Fuse protection, external	A	2A time lag
Managed breakdowns		Overload and electronics overheating, cable breakdown, supply voltage failures
Electromagnetic compatibility (EMC) emissions EN 61000-6-4, immunity EN 61000-6-2		According to 2014/30/EU standards

**NOTE:** The IP degree is guaranteed only with mating connector of equivalent IP degree, installed and tightened correctly. Moreover, on the GH versions it is necessary to protect any unused connections with caps.

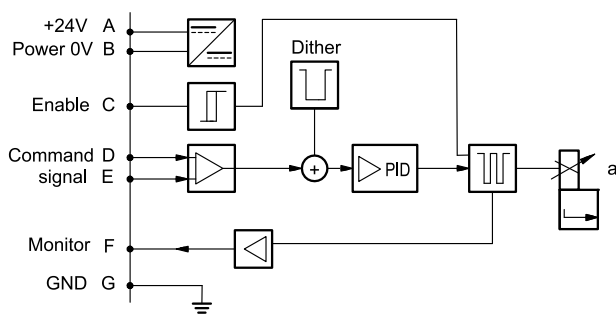
## 4 - PRE\*G - STANDARD ELECTRONICS

### 4.1 - Electrical characteristics

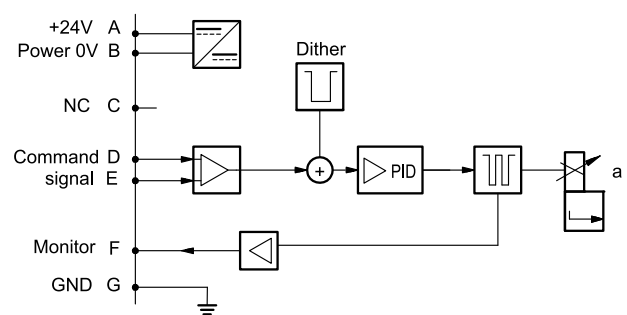
Command signal:	voltage (E0) current (E1)	V DC mA	0 ÷ 10 (impedance Ri > 11 kOhm) 4 ÷ 20 (impedance Ri = 58 Ohm)
Monitor signal (current to solenoid):	voltage (E0) current (E1)	V DC mA	0 ÷ 10 (impedance Ro > 1 kOhm) 4 ÷ 20 (impedance Ro = 500 Ohm)
Communication for diagnostic			LIN-bus Interface (by means of the optional kit)
Connection			6 pin + PE (MIL-C-5015-G - DIN EN 175201-804)

### 4.2 - On-board electronics diagrams

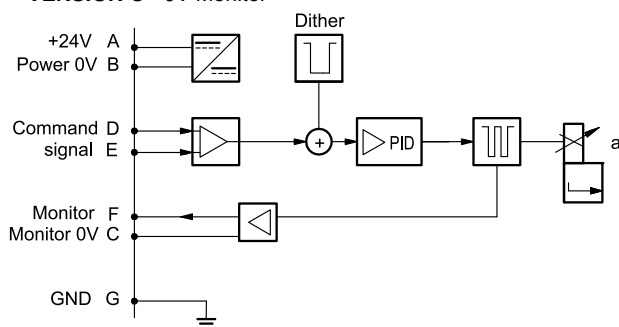
#### VERSION A - External Enable



#### VERSION B - Internal Enable

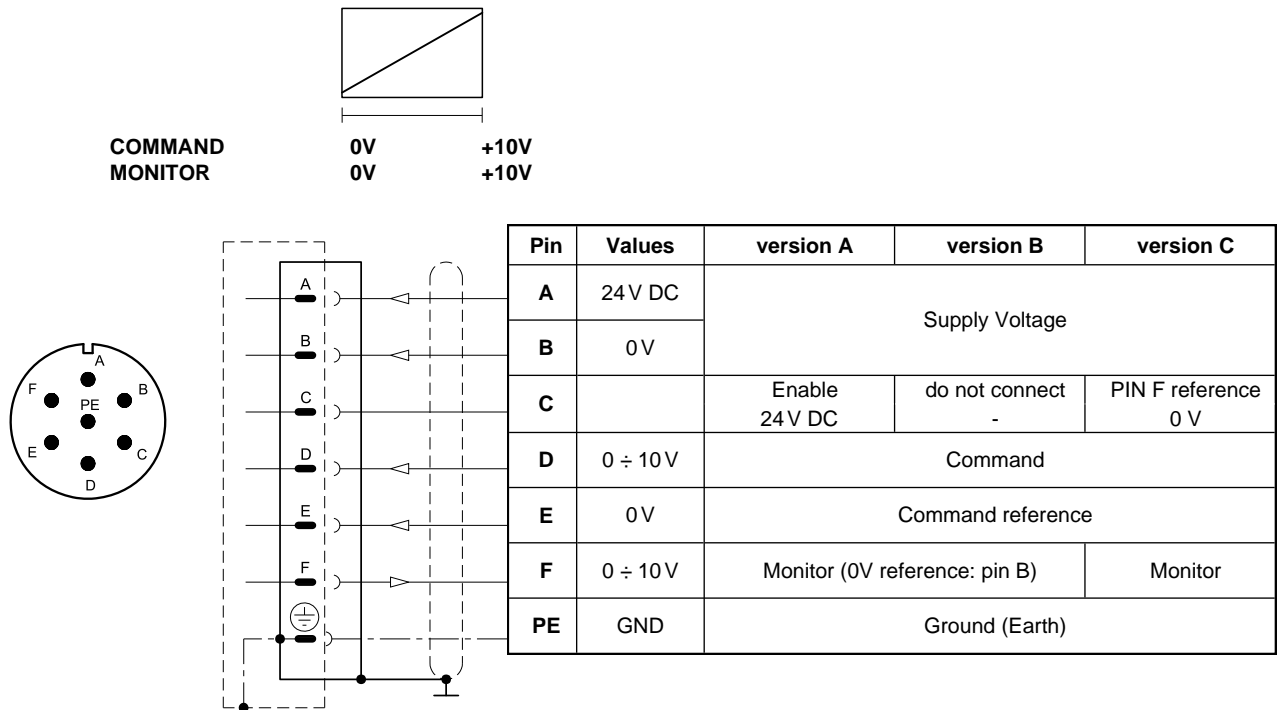


#### VERSION C - 0V Monitor



#### 4.3 - Versions with voltage command (E0)

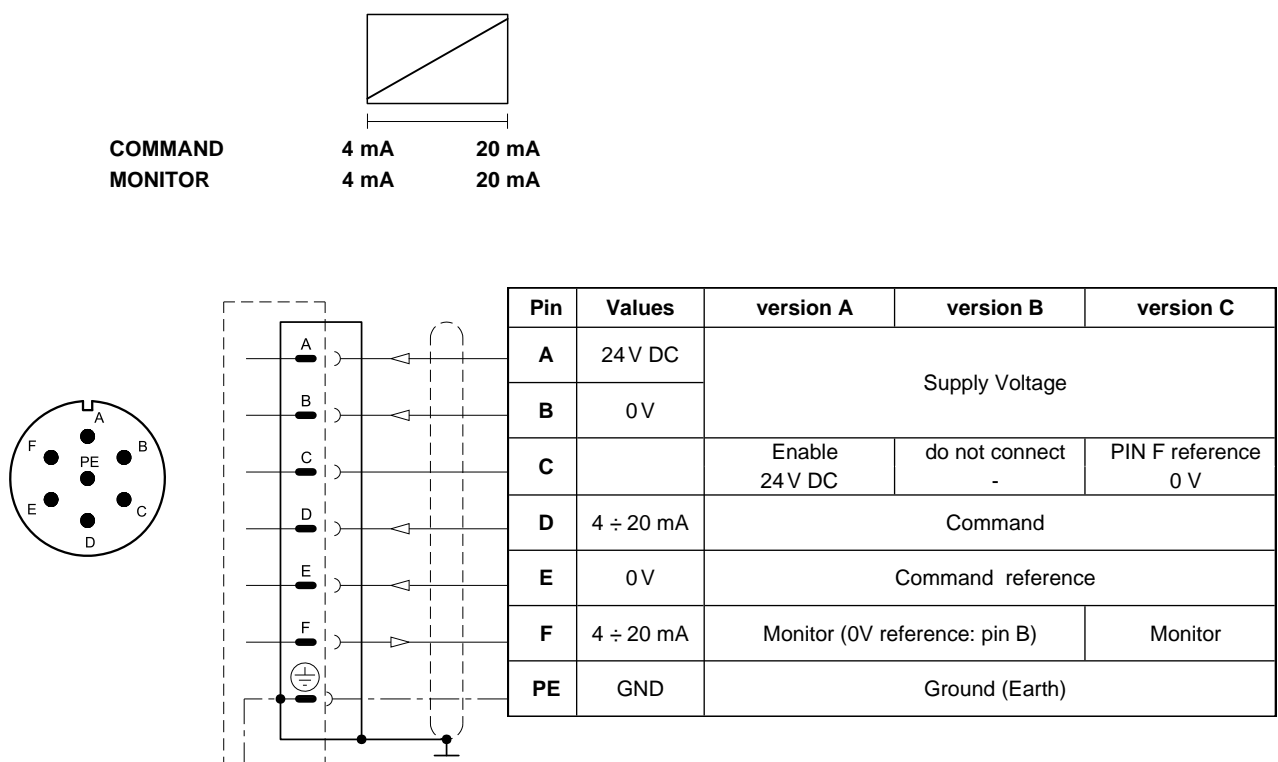
The reference signal is between  $0 \div 10V$ . The monitor feature of versions B and C becomes available with a delay of 0.5 sec from the power-on of the card.



#### 4.4 - Versions with current command (E1)

The reference signal is supplied in current  $4 \div 20$  mA. If the current for command is lower, the card shows a breakdown cable error. To reset the error is sufficient to restore the signal.

The monitor feature of versions B and C becomes available with a delay of 0,5 sec from the power-on of the card.



## 5 - PRE\*GL - COMPACT ELECTRONICS


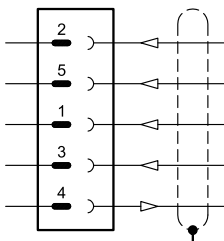
In IO-Link networks, the length of the connecting cables is limited to 20 metres. In CA versions, pin 3 and pin 5 are galvanic isolated up to 100 V to avoid earth loops.

### 5.1 - Electrical characteristics

Command signal:	voltage (E0) current (E1)	V DC mA	0 ÷ 10 (impedance $R_i > 11 \text{ k}\Omega$ ) 4 ÷ 20 (impedance $R_i = 58 \text{ }\Omega$ )
Monitor signal (current to solenoid):	voltage (E0) current (E1)	V DC mA	0 ÷ 5 (impedance $R_o > 1 \text{ k}\Omega$ ) 4 ÷ 20 (impedance $R_o = 500 \text{ }\Omega$ )
IO-Link communication (IOL):	Data rate	kBaud	IO-Link Port Class B 38.4
Can Open communication (CA):	Data rate	kbit	10 ÷ 1000
Data register (IOL and CA versions only)			card voltage supply, solenoid faults (shortcircuit, bad configuration), box temperature.
Connection			5-pin M12 code A (IEC 61076-2-101)


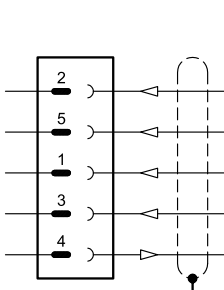
### 5.2 - Pin tables

#### 'E0' connection


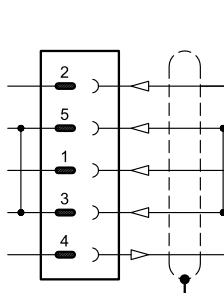
Pin	Values	Function
2	24 V DC	Supply voltage (solenoid and logic)
5	0 V	
1	0 ÷ 10 V	Command
3	0 V	Command reference
4	0 ÷ 5 V	Monitor (0V reference: pin 5)

#### 'E1' connection

Pin	Values	Function
2	24 V DC	Supply voltage (solenoid and logic)
5	0 V	
1	4 ÷ 20 mA	Command
3	0V	Command reference
4	4 ÷ 20 mA	Monitor (0V reference: pin 5)


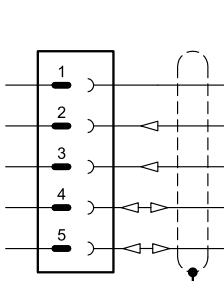
#### 'IOL' connection

Pin	Values	Function
2	2L+ 24 V DC	Solenoid supply voltage
5	2L- 0 V (GND)	
1	1L+ +24 V DC	Logic and IO-Link supply voltage
3	1L- 0V (GND)	
4	C/Q	IO-Link Communication

**NOTE:** Pin 3 and pin 5 are linked with each other in the valve electronics. The reference potentials 1L- and 2L- of the two supply voltages must also be linked with each other on the customer side.

#### 'CA' connection

Pin	Values	Function
1	CAN_SH	Shield
2	24 V DC	Supply voltage
3	0 V (GND)	
4	CAN_H	Bus line (high)
5	CAN_L	Bus line (low)

## 6 - PRE\*GH - FIELDBUS ELECTRONICS

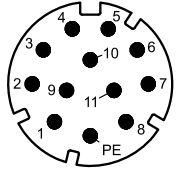
The 11+ PE pin connection allows separate supply voltage for electronics and solenoids.

Command - valve position schemes as for the standard electronics. Please refer to pictures in p. 4.3 and 4.4.

### 6.1 - Electrical characteristics

Command signal:	voltage (E0) current (E1) digital (FD)	V DC mA	0 ÷ 10 (impedance Ri > 11 kOhm) 4 ÷ 20 (impedance Ri = 58 Ohm) via fieldbus
Monitor signal (current to solenoid):	voltage (E0) current (E1)	V DC mA	0 ÷ 10 (impedance Ro > 1 kOhm) 4 ÷ 20 (impedance Ro = 500 Ohm)
Communication / diagnostic			via Bus register
Communication interface standards			IEC 61158
Communication physical layer			fast ethernet, insulated 100 Base TX
Power connection			11 pin + PE (DIN 43651)

### 6.2 - X1 Main connection pin table



**D1: one command**

Pin	Values	Function
1	24 V DC	Main supply voltage
2	0 V	
3	24V DC	Enable
4	0 ÷ 10 V (E0) 4 ÷ 20 (E1)	Command
5	0 V	Command reference signal
6	0 ÷ 10 V (E0) 4 ÷ 20 (E1)	Monitor (0V reference pin 10)
7	NC	do not connect
8	NC	do not connect
9	24 V DC	Logic and control supply
10	0 V	
11	24 V DC	Fault (0V DC) or normal working (24V DC) (0V reference pin 2)
12	GND	Ground (Earth)

**D0: full digital**

Pin	Values	Function
1	24 V DC	Main supply voltage
2	0 V	
3	24V DC	Enable
4	NC	do not connect
5	NC	do not connect
6	NC	do not connect
7	NC	do not connect
8	NC	do not connect
9	24 V DC	Logic and control supply
10	0 V	
11	24 V DC	Fault (0V DC) or normal working (24V DC) (0V reference pin 2)
12	GND	Ground (Earth)

### 6.3 - FIELDBUS connections

Please wire following guidelines provided by the related standards communication protocol. Any connections present and not used must be protected with special caps so as not to nullify the protection against atmospheric agents.

**X2 (IN) connection:** M12 D 4 pin female



Pin	Values	Function
1	TX+	Transmitter
2	RX+	Receiver
3	TX-	Transmitter
4	RX-	Receiver
HOUSING	shield	

**X3 (OUT) connection:** M12 D 4 pin female



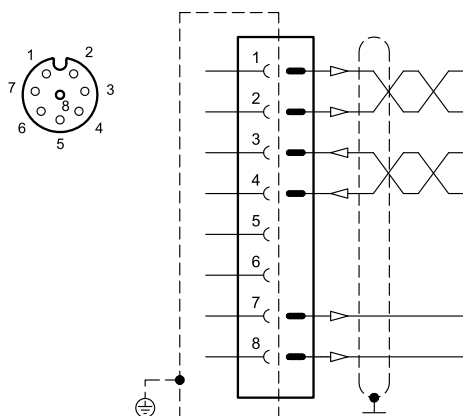
Pin	Values	Function
1	TX+	Transmitter
2	RX+	Receiver
3	TX-	Transmitter
4	RX-	Receiver
HOUSING	shield	

**NOTE:** Shield connection on connector housing is recommended.

## 6.4 - Digital transducer connection

**X7 connection:** M12 A 8 pin female

**VERSION 1: SSI type**



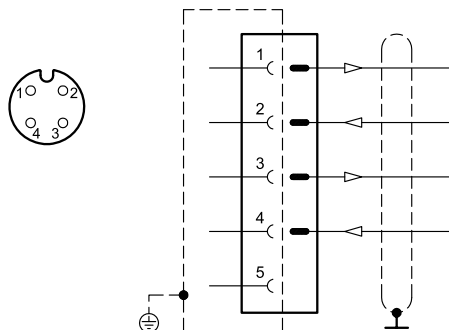
Pin	SSI Values	Function	Notes
1	CLK+	Serial synchronous clock (+)	Input - digital signal
2	CLK-	Serial synchronous clock (-)	
3	MISO+	Serial position data (+)	
4	MISO-	Serial position data (-)	
5	NC	-	do not connect
6	NC	-	
7	+24 V	transducer power supply	Output power supply
8	0 V	-	Common GND

## 6.5 - Analogue transducer connection

**X4 connection:** M12 A 4 pin female

**VERSION 1: single / double transducer**

(single or double is a software-selectable option)



Pin	Values	Notes
1	+24 V	Remote transducer power supply (out) 100 mA
2	$\pm 10 \text{ V}$ $4 \div 20 \text{ mA}$	Input signal of transducer 1 (range software selectable)
3	0 V	Common reference signal for transducer power and signals
4	$\pm 10 \text{ V}$ $4 \div 20 \text{ mA}$	Input signal of transducer 2 (range software selectable)
5	-	

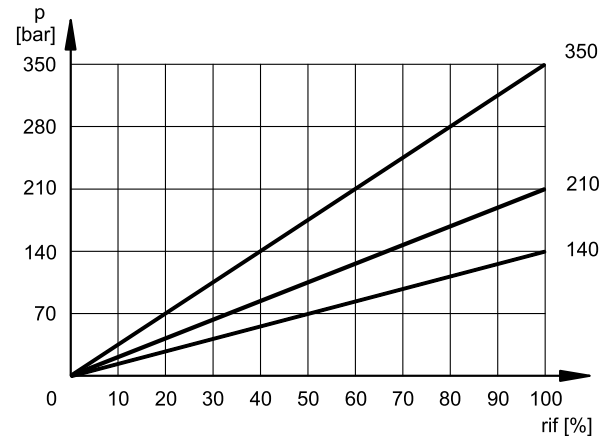
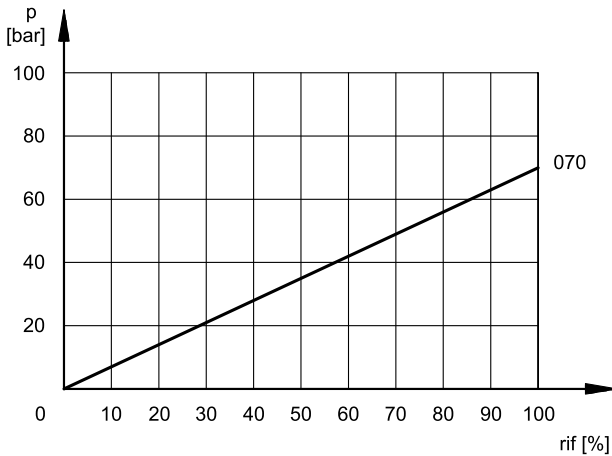


## 7 - CHARACTERISTIC CURVES

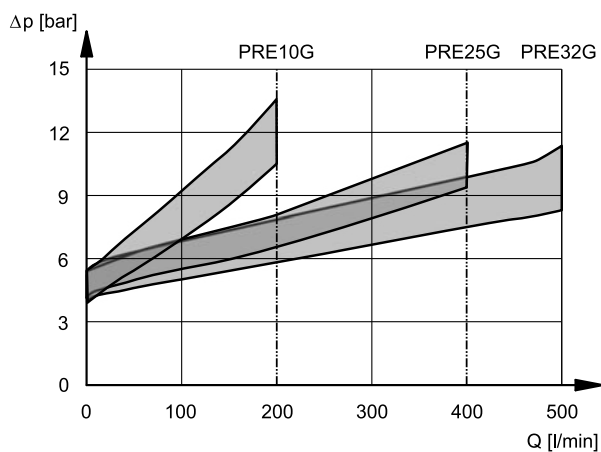
(obtained with mineral oil with viscosity of 36 cSt at 50°C)

Typical control characteristics, according to the reference signal for available pressure control ranges, measured with input flow rate  $Q = 50$  l/min. Characteristic curves measured without backpressure in T, with linearity compensation set by the onboard electronics.

**PRESSURE CONTROL  $p = f(I)$**

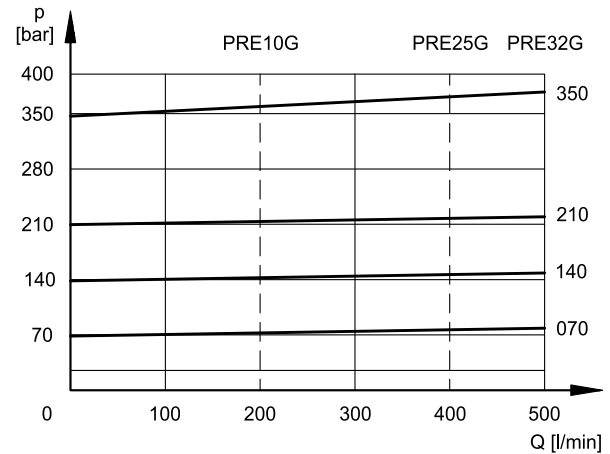


**MINIMUM CONTROLLED PRESSURE  $p_{min} = f(Q)$**



minimum regulated pressure for pressure control ranges between 70 bar and 350 bar.

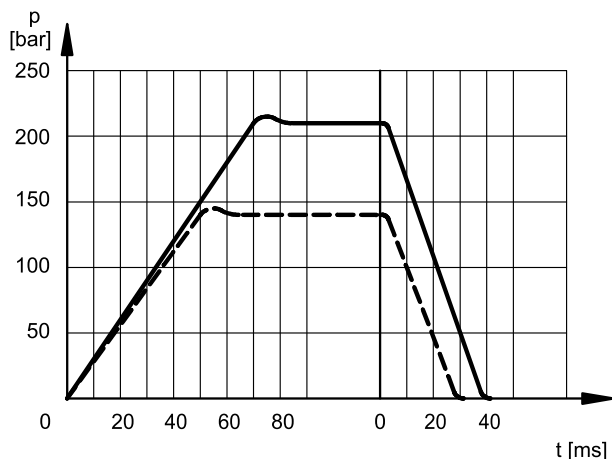
**PRESSURE VARIATION  $p_{max} = f(Q)$**



## 8 - STEP RESPONSE

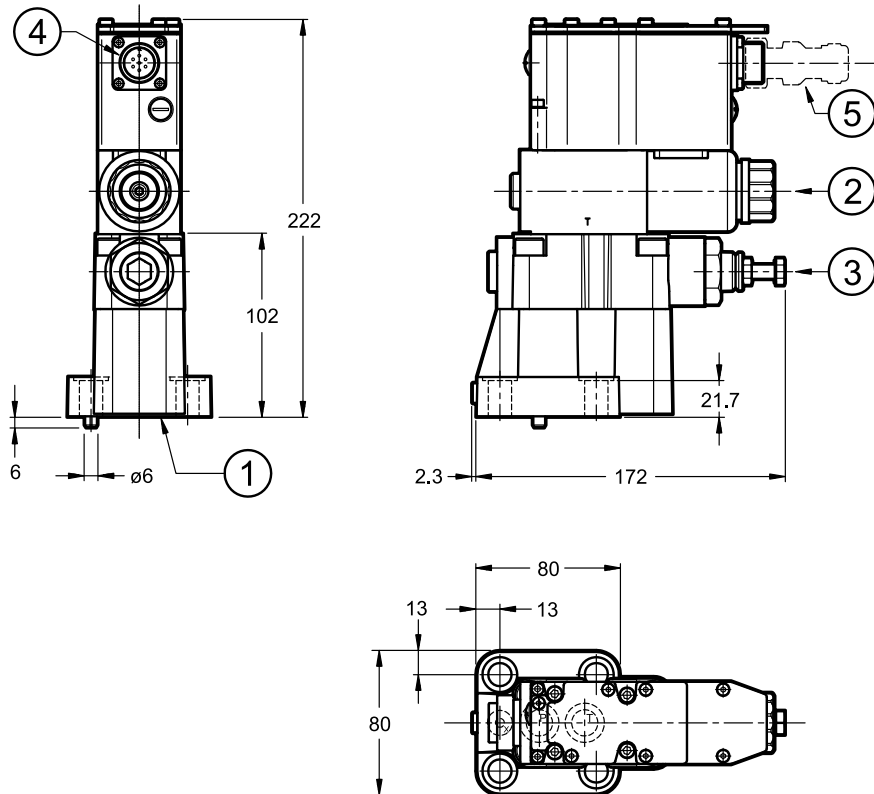
(obtained with mineral oil with viscosity of 36 cSt at 50°C)

Response times obtained withh PRE\*G-210 valves, with an input flow rate of 50 l/min and a pressure oil volume of 2 litres. The response time is affected both by the flow rate and the oil volume in the pipework.

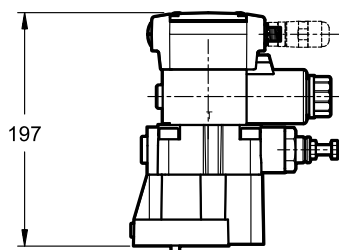


## 9 - PRE10G\* - OVERALL AND MOUNTING DIMENSIONS

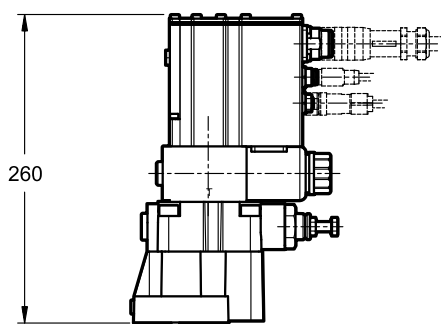
dimensions in mm



**PRE10GL**



**PRE10GH**



**NOTE 1:** at the first start up, or after a long period of no use, it is necessary to vent the air through the breather (2) placed at the end of the solenoid tube.

**NOTE 2:** Mounting interface at point 12.

1	Mounting surface with sealing rings: 2 OR type 123 (17.86x2.62) - 90 Shore 1 OR type 109 (9.13x2.62) - 90 Shore
2	Breather: Allen key 4
3	Factory-set pressure relief valve
4	Main connection 6 pin + PE
5	Mating connector <b>To be ordered separately.</b> See catalogue 89 000

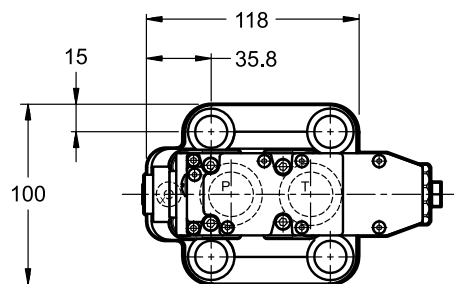
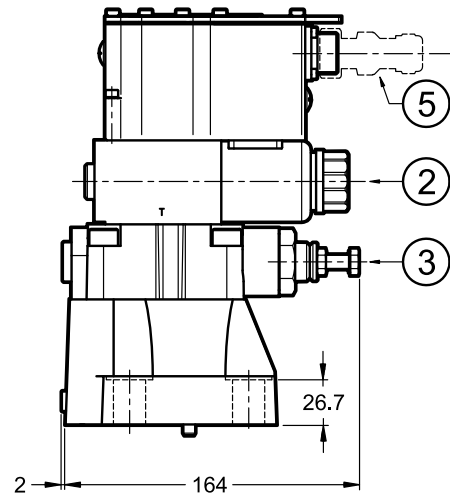
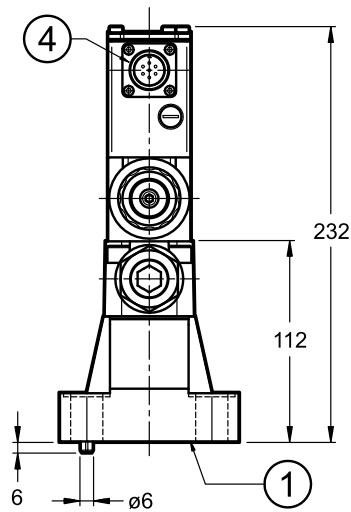
Valve fastening: 4 SHCS M12x40 - ISO 4762

Torque: 69 Nm (screws A8.8)

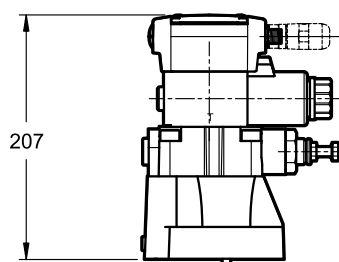
Thread of mounting holes: M12x20

10 - PRE25G\* - OVERALL AND MOUNTING DIMENSIONS

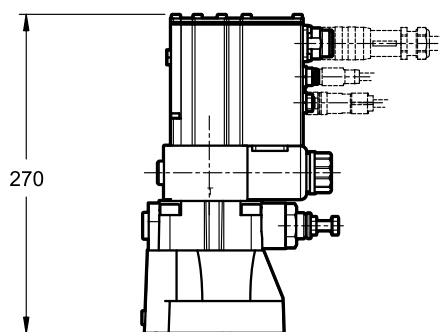
dimensions in mm



PRE25GL



PRE25GH



**NOTE 1:** at the first start up, or after a long period of no use, it is necessary to vent the air through the breather (2) placed at the end of the solenoid tube.

**NOTE 2:** Mounting interface at point 12.

1	Mounting surface with sealing rings: 2 OR type 3118 (29.82x2.62) - 90 Shore 1 OR type 109 (9.13x2.62) - 90 Shore
2	Breather: Allen key 4
3	Factory-set pressure relief valve
4	Main connection 6 pin + PE
5	Mating connector <b>To be ordered separately.</b> See catalogue 89 000

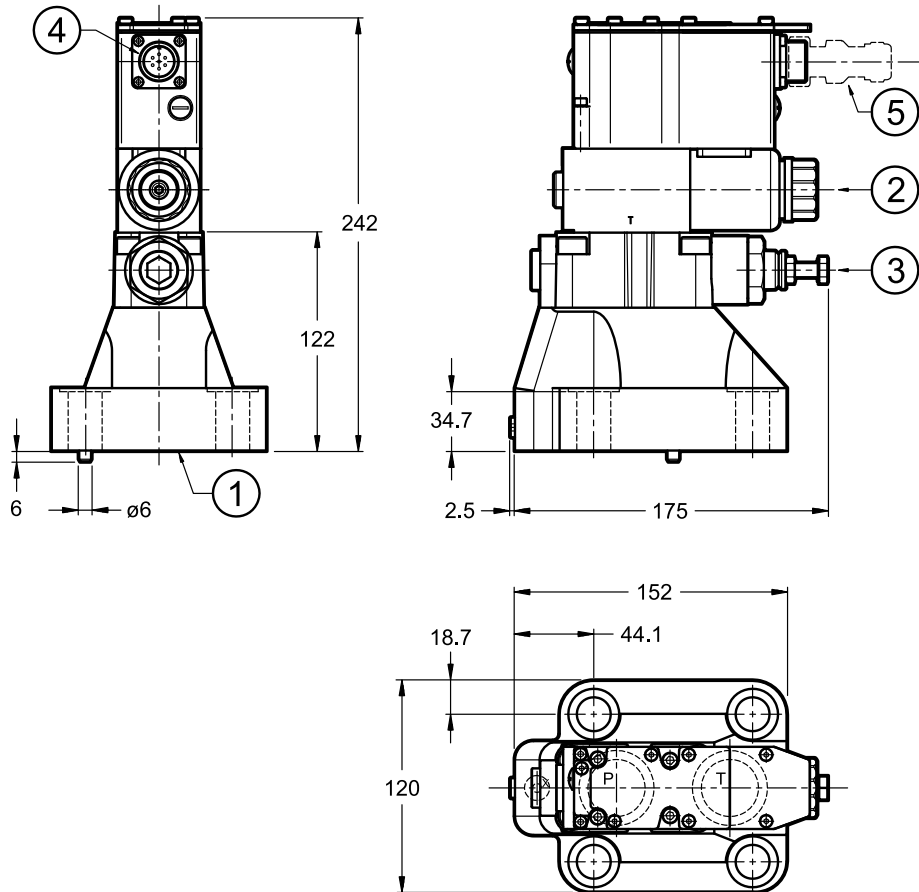
Valve fastening: 4 SHCS M16x60 - ISO 4762

Torque: 170 Nm (screws A8.8)

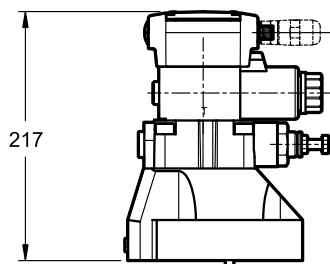
Thread of mounting holes: M16x25

## 11 - PRE32G\* - OVERALL AND MOUNTING DIMENSIONS

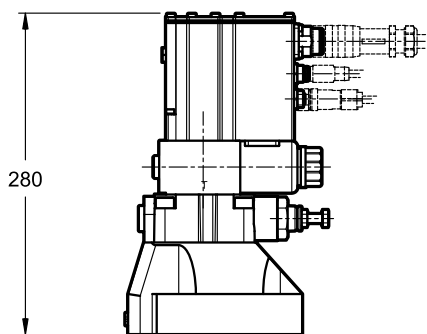
dimensions in mm



PRE32GL



PRE32GH



**NOTE 1:** at the first start up, or after a long period of no use, it is necessary to vent the air through the breather (2) placed at the end of the solenoid tube.

**NOTE 2:** Mounting interface at point 12.

1	Mounting surface with sealing rings: 2 OR type 4137 (34.52x3.53) - 90 Shore 1 OR type 109 (9.13x2.62) - 90 Shore
2	Breather: Allen key 4
3	Factory-set pressure relief valve
4	Main connection 6 pin + PE
5	Mating electrical connector <b>To be ordered separately.</b> See catalogue 89 000

Valve fastening: 4 SHCS M18x60 - ISO 4762

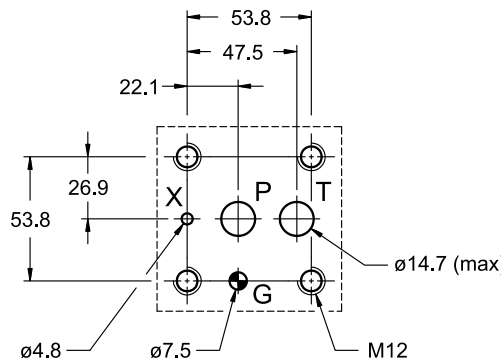
Torque: 235 Nm (screws A8.8)

Thread of mounting holes: M18x27

## 12 - MOUNTING INTERFACES

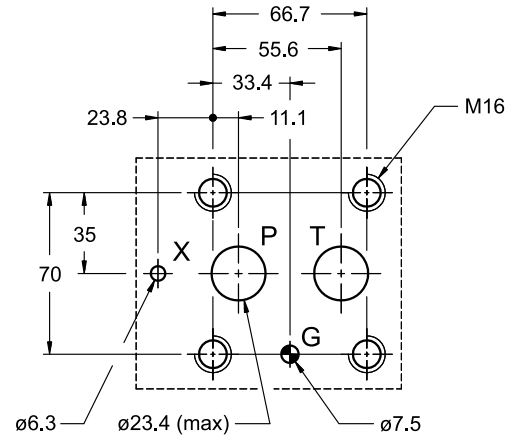
### PRE10G\*:

ISO 6264-06-09-\*97  
(CETOP 4.4.2-2-R06-350)



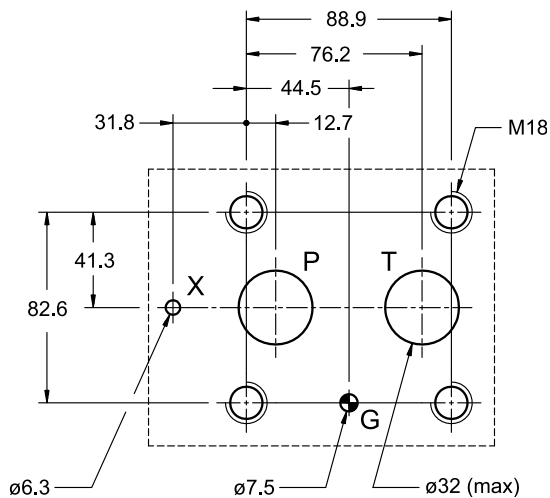
### PRE25G\*:

ISO 6264-08-13-\*97  
(CETOP 4.4.2-2-R08-350)



### PRE32G\*:

ISO 6264-10-17-\*97  
(CETOP 4.4.2-2-R10-350)



## 13 - HYDRAULIC FLUIDS

Use mineral oil-based hydraulic fluids HL or HM type, according to ISO 6743-4. For these fluids, use NBR seals. For fluids HFDR type (phosphate esters) use FPM seals (code V). For the use of other kinds of fluid such as HFA, HFB, HFC, please consult our technical department.

Using fluids at temperatures higher than 80 °C causes a faster degradation of the fluid and of the seals characteristics. The fluid must be preserved in its physical and chemical characteristics.

## 14 - INSTALLATION

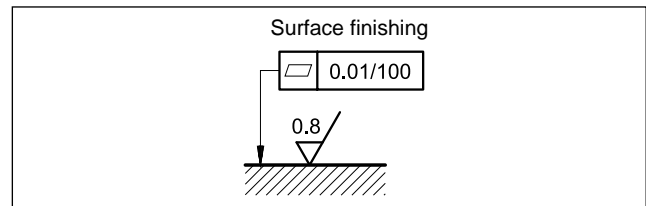
We recommend to install the valves either in horizontal position, or vertical position with the solenoid downward. If the valve is installed in vertical position and with the solenoid upward, you must consider possible variations of the minimum controlled pressure, if compared to what is indicated in point 7.

Ensure that there is no air in the hydraulic circuit. In particular applications, can be necessary to vent the air entrapped in the solenoid tube, by using the appropriate drain screw in the solenoid tube.

Ensure the solenoid tube is always filled with oil. At the end of the operation, make sure of having correctly replaced the drain screw. Connect the valve T port directly to the tank.

**Add any backpressure value detected in the T line to the controlled pressure value. Maximum admissible backpressure in the T line, under operational conditions, is 2 bar.**

Valves are fixed by means of screws or tie rods on a flat surface with planarity and roughness equal to or better than those indicated in the relative symbols. If minimum values are not observed, fluid can easily leak between the valve and support surface.



## 15 - ACCESSORIES

(to be ordered separately)

### 15.1 - Mating connectors

Mating connectors must be ordered separately. See catalogue 89 000.



For K11 and K16 versions we recommend the choice of a metal connector to avoid electromagnetic disturbances and to comply with EMC regulations on electromagnetic compatibility. If you opt for a plastic connector, make sure that it guarantees and maintains the IP and EMC protection characteristics of the valve.

### 15.2 - Mating connectors and caps for fieldbus communication and for sensors.

Duplomatic offers spare parts to be wired and also ready-to-use cord sets. Please refer to cat. 89 000.

### 15.3 - Connection cable

The optimal wiring provides for 7 isolated conductors, with separate screen for the signal wires (command, monitor) and an overall screen.

Cross section for power supply:

- up to 20 m cable length : 1,0 mm<sup>2</sup>
- up to 40 m cable length : 1,5 mm<sup>2</sup> (IO-Link excluded)

Cross section for signals (command, monitor):

- 0,50 mm<sup>2</sup>

### 15.4 - Kit for start-up LINPC-USB

Device for service start-up and diagnostic. See catalogue 89 850.

## 16 - SUBPLATES

(see catalogue 51 000)

	PRE10G*	PRE25G*	PRE32G*
Type	PMRQ3-AI4G rear ports	PMRQ5-AI5G rear ports	PMRQ7-AI7G rear ports
P, T port dimensions	P: 1/2" BSP T: 3/4" BSP	1" BSP	1" ¼ BSP
X port dimensions	1/4" BSP	1/4" BSP	1/4" BSP